

# Ambiguous Business Cycles

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# Motivation

- Role of uncertainty shocks in business cycles?
- usually: uncertainty = risk
- ⇒ agents confident in probability assessments
- ⇒ shocks to uncertainty = shocks to volatility
- this paper: uncertainty = risk + *ambiguity* (*Knightian uncertainty*)
- ⇒ allows for lack of confidence in prob assessments
- ⇒ shocks to uncertainty can be shocks to confidence

# Overview

- Standard business cycle model with ambiguity aversion
  - ▶ recursive multiple priors preferences
  - ▶ ambiguity about mean aggregate productivity
  - ⇒ 1st order effects of uncertainty
- Methodology
  - ▶ study uncertainty shocks with 1st order approximation
  - ▶ simple estimation strategy based on linearization
  - ▶ motivate & bound set of priors by concern w/ nonstationarity
- Properties
  - ▶ ambiguity shocks work like “unrealized” news shocks with bias.
  - ▶ in medium scale DSGE model estimated on US data, ambiguity shocks
    - ★ generate comovement and account for  $> \frac{1}{2}$  of fluctuations in  $Y, C, I, H$ .
    - ★ imply countercyclical asset premia.

# Literature

- 1 **Multiple Priors Utility:** Gilboa-Schmeidler (1989), Epstein and Wang (1994), Epstein and Schneider (2003).
- 2 **Business cycles with preference for robustness:** Hansen, Sargent and Tallarini (1999), Cagetti, Hansen, Sargent and Williams (2002), Smith and Bidder (2011).
- 3 **Signals:** Beaudry and Portier (2006), Christiano, Ilut, Motto and Rostagno (2008), Schmitt-Grohe and Uribe (2008), Jaimovich and Rebelo (2009), Lorenzoni (2009), Blanchard, L'Huillier and Lorenzoni (2010), Barsky and Sims (2010, 2011).
- 4 **Risk shocks:** Justiniano and Primiceri (2007), Fernandez-Villaverde and Rubio-Ramirez (2007), Bloom (2009), Bloom, Floetotto and Jaimovich (2009), Christiano, Motto and Rostagno (2010), Gourio (2010), Arellano, Bai and Kehoe (2010), Basu and Bundick (2011)
- 5 **Shocks to 'non-fundamentals':** Farmer (2009), Angeletos and La'O (2011), Martin and Ventura (2011).

# Ambiguity aversion & preferences

- $S$  = state space
  - ▶ one element  $s \in S$  realized every period
  - ▶ histories  $s^t \in S^t$
- Consumption streams  $C = (C_t(s^t))$
- Recursive multiple-priors utility (Epstein and Schneider (2003))

$$U_t(C; s^t) = u(C_t(s^t)) + \beta \min_{p \in \mathcal{P}_t(s^t)} E^p [U_{t+1}(C; s^{t+1})],$$

- Primitives:
  - ▶ felicity  $u$  (possibly over multiple goods) & discount factor  $\beta$
  - ▶ one-step-ahead belief sets  $\mathcal{P}_t(s^t)$  – size captures (lack of) confidence
- Why this functional form?
  - ▶ preference for known odds over unknown odds (Ellsberg Paradox)
  - ▶ formally, weaken Independence Axiom

# A stylized business cycle model with ambiguity

- Representative agent with recursive multiple priors utility.
- Felicity from consumption, hours

$$u(C_t, N_t) = \frac{C_t^{1-\gamma}}{1-\gamma} - \beta N_t$$

- Output  $Y_t$  produced by

$$Y_t = Z_t N_{t-1}$$

- Labor chosen one period in advance
- Belief sets that enter utility
  - ▶ specify ambiguity about exogenous productivity
  - ▶ beliefs about endogenous variables derived from “structural knowledge” of economy
  - ▶ true TFP process: iid lognormal with  $E[Z_t] = 1$ ,  $\text{var}(\log Z_t) = \sigma_Z^2$

## Belief set: time variation in ambiguity

- Agents experience changes in confidence, described by process  $a_t$
- ⇒ Representation of one-step-ahead belief set  $\mathcal{P}_t$

$$\log Z_{t+1} = \mu_t - \frac{1}{2}\sigma_z^2 + \sigma_z \varepsilon_{z,t+1}$$
$$\mu_t \in [-a_t, a_t]$$

- Examples for evolution of (lack of) confidence  $a_t$ 
  - Linear, homoskedastic law of motion

$$a_t = (1 - \rho_a) \bar{a} + \rho_a a_{t-1} + \varepsilon_{a,t}$$

Interpretation: intangible information affects confidence

- Feedback from realized volatility

$$a_t = \sqrt{2\eta} \sigma_{z,t}$$

Interpretation: observed turbulence lowers confidence

Follows if  $\mathcal{P}_t$  is "constant entropy" ball around true DGP:

$$\mu_t \in [-a_t, a_t] \Leftrightarrow R_t = \frac{\mu_t^2}{2\sigma_{z,t}^2} \leq \eta$$

# Social planner problem

- Bellman equation

$$V(N, Z, a) = \max_{N'} \left[ u(ZN, N') + \beta \min_{\mu \in [-a, a]} E^{\mu} V(N', Z', a') \right]$$

- Worst-case belief: future technology is low

$$\mu^* = -a$$

⇒ planner acts as if bad times ahead

- Interpretation: precautionary behavior
- First order effects of ambiguity.



# Characterizing equilibrium

## Two Steps

- 1 Solve planner problem under worst case belief  $\mu^* = -a$   
Optimal hours from FOC

$$1 = E^{-a} \left[ \beta (Z' N')^{-\gamma} Z' \right]$$

- 2 Characterize variables under true shock process (in logs)

$$n_t = -(1/\gamma - 1) \left( a_t + \frac{1}{2} \gamma \sigma_z^2 \right)$$

$$y_{t+1} = z_{t+1} + n_t$$

⇒ Worst case belief reflected in action  $n_t$ , but not in shock realization  $z_{t+1}$

# Properties of equilibrium

- Dynamics

$$y_{t+1} = z_{t+1} + n_t$$

$$n_t = -(1/\gamma - 1)(a_t + \frac{1}{2}\gamma\sigma_z^2)$$

$$a_t = (1 - \rho_a)\bar{a} + \rho_a a_{t-1} + \varepsilon_{a,t}$$

- ▶ first order effects of uncertainty on output, even as  $\sigma_z^2 \rightarrow 0$
- ▶ if substitution effect is strong enough ( $1/\gamma > 1$ ):

- 1 loss of confidence generates a recession
- 2 increase in confidence leads to an expansion

- ▶ TFP is not unusual in either cases
- ▶ hours do not forecast TFP if  $cov(a_t, z_{t+1}) = 0$

- Asset prices reflect time varying ambiguity premia

- ▶ price of 1-step-ahead consumption claim =  $\frac{E_t C_{t+1}}{R_t^f} \exp(-a_t - \gamma\sigma_z^2)$

## Comparison of shocks

- Ambiguity shocks  $n_t = -(1/\gamma - 1)(a_t + \frac{1}{2}\gamma\sigma_z^2)$ 
  - ▶ loss of confidence generates recession if  $1/\gamma > 1$
  - ▶ hours do not forecast TFP: regress  $z_{t+1}$  on  $n_t$  to get slope 0
  - ▶ time varying ambiguity premium on consumption claim =  $a_t$
- News & noise shocks  $n_t = (1/\gamma - 1)(\pi s_t - \frac{1}{2}\gamma(1 - \pi)\sigma_z^2)$ 
  - ▶ signal about productivity  $s_t = z_{t+1} + \sigma_s\epsilon_{s,t}$  with  $\pi := \sigma_z^2/(\sigma_z^2 + \sigma_s^2)$
  - ▶ bad signal (news or noise) generates recession if  $1/\gamma > 1$
  - ▶ hours forecast TFP: regress  $z_{t+1}$  on  $n_t$  to get slope  $\gamma/(1 - \gamma)$
  - ▶ constant risk premium on consumption claim
- Volatility shocks  $n_t = -(1/\gamma - 1)\frac{1}{2}\gamma\sigma_{z,t}^2$ 
  - ▶ volatility process  $\sigma_{z,t}^2 = \text{var}_t(z_{t+1})$ , mean adjusts so  $E_t Z_{t+1} = 1$
  - ▶ volatility increase generates recession if  $1/\gamma > 1$
  - ▶ hours do not forecast TFP (but forecast turbulence)
  - ▶ time varying risk premium on consumption claim =  $\gamma\sigma_{z,t}^2$

# General framework: Rep. agent & Markov uncertainty

- Notation (as before  $s =$  exogenous state)
  - ▶  $X =$  endogenous states (e.g. capital)
  - ▶  $A =$  agent actions (e.g. consumption, investment)
  - ▶  $Y =$  other endogenous variables (e.g. prices)
- Recursive equilibrium
  - ▶ Functions for actions  $A$ , other endog vars  $Y$ , value  $V$  s.t., for all  $(X, s)$ :

$$V(X, s) = \max_{A \in B(Y, X, s)} \left\{ u(c(A)) + \beta \min_{p \in \mathcal{P}(s)} E^p [V(X', s')] \right\}$$
$$\text{s.t. } X' = T(X, A, Y, s, s')$$

- ▶ endog var determination:  $G(A, Y, X, s) = 0$
  - ▶ true exogenous Markov state process  $p^*(s) \in \mathcal{P}(s)$
- Analysis again in 2 steps
  - ▶ find recursive equilibrium
  - ▶ characterize variables under “true” state process

# Characterizing equilibrium: a guess-and-verify approach

- basic idea
  - ① guess the worst case belief  $p^0$
  - ② find recursive equilibrium under expected utility & belief  $p^0$
  - ③ compute value function under worst case belief, say  $V^0$
  - ④ verify that the guess  $p^0$  indeed achieves the minimum
- “essentially linear” economies & productivity shocks
  - ▶ environment  $T, B, G$  s.t. 1st order approx. ok *under expected utility*
  - ▶ ambiguity is about mean of innovations to  $s$
- simplification in essentially linear case
  - ▶ in step 1, guess that worst case mean is linear in state variables
  - ▶ step 2 uses loglinear approximation around “zero risk” steady state (sets risk to zero, but retains worst case mean)
  - ▶ step 4 then checks monotonicity of value function

# An estimated DSGE model with ambiguity

- Similar to CEE (2005), SW (2007)
- ① Intermediate goods producers
  - ▶ Price setting monopolist; competitive in the factor markets
    - ★ mark-up shocks.
- ② Final goods producers.
  - ▶ Combines intermediate goods to produce a homogenous good.
- ③ Households: **ambiguity-averse**
  - ▶ Own capital stock, consume, monopolistically supply specialized labor
  - ▶ investment adjustment costs, internal habit in consumption.
    - ★ efficiency of investment and price of investment shocks.
- ④ “Employment agencies”
  - ▶ aggregate specialized labor into homogenous labor.
- ⑤ Government
  - ▶ Taylor-type interest rule: reacts to inflation, output gap and growth.
    - ★ government spending and monetary policy shocks.

# Technology

- The intermediate good  $j$  is produced using the function:

$$Y_{j,t} = Z_t K_{j,t}^\alpha (\epsilon_t L_{j,t})^{1-\alpha} - F_t$$

- Final goods:

$$Y_t = \left[ \int_0^1 Y_{j,t}^{\frac{1}{\lambda_{f,t}}} dj \right]^{\lambda_{f,t}}$$

- Capital accumulation:

$$\bar{K}_{t+1} = (1 - \delta)\bar{K}_t + \left[ 1 - S \left( \zeta_t \frac{I_t}{I_{t-1}} \right) \right] I_t.$$

- Beliefs about technology:

$$\log Z_{t+1} = \rho_z \log Z_t + \mu_t + \sigma_u \varepsilon_{z,t+1}$$

$$\mu_t \in [-a_t, a_t]$$

$$a_t - \bar{a} = \rho_a (a_{t-1} - \bar{a}) + \sigma_a \varepsilon_{a,t}$$

# A bound on ambiguity

- Beliefs about technology

$$\log Z_{t+1} = \rho_z \log Z_t + \mu_t + \sigma_u \varepsilon_{z,t+1}$$

$$\mu_t \in [-a_t, a_t]$$

$$a_t - \bar{a} = \rho_a (a_{t-1} - \bar{a}) + \sigma_a \varepsilon_{a,t}$$

- ▶ agents view innovations as risky ( $\sigma_u \varepsilon_{z,t+1}$ ) and ambiguous ( $\mu_t$ )
- ▶ they know empirical moments of true  $\{\mu_t^*\}$ , but not the exact sequence
- ▶ empirical moments say  $\log Z_{t+1} - \rho_z \log Z_t \sim i.i.N(0, \sigma_z^2)$ ;  $\sigma_z^2 > \sigma_u^2$
- ▶ agents respond to uncertainty about  $\mu_t^*$  as if minimizing over  $[-a_t, a_t]$

- Constrain  $a_t$  to lie in a maximal interval  $[-a^{\max}, a^{\max}]$

- ▶ require that “boundary” beliefs  $\pm a_{\max}$  imply “good enough” forecasts:
- ▶ there exists  $\sigma_u^2$  s.t. for every potential true DGP  $\{\mu_t^*\}$ ,  $a_{\max}$  or  $-a_{\max}$  is best forecasting rule at least  $\alpha$  of the time
- ▶  $a_{\max}$  is best forecasting rule at date  $t$  if true mean  $\mu_t^* > a_{\max}$
- ▶ for example,  $\alpha = 5\%$  implies  $a_{\max} = 2\sigma_z =$  bound used in estimation



# Estimation

- Linearization → estimation using standard Kalman filter methods.
- Data: US 1984Q1-2010Q1: Output, consumption, investment, price of investment growth, hours, FFR, inflation.
- Law of motion for  $a_t$  is estimated
- Estimates:

- ▶ productivity dynamics

$$\rho_z = 0.95, \sigma_z = 0.0045$$

- ▶ confidence dynamics

$$\bar{a} = 0.0043, \rho_a = 0.96, \sigma_a = 0.00041$$

- ▶ other parameters broadly consistent with previous studies.

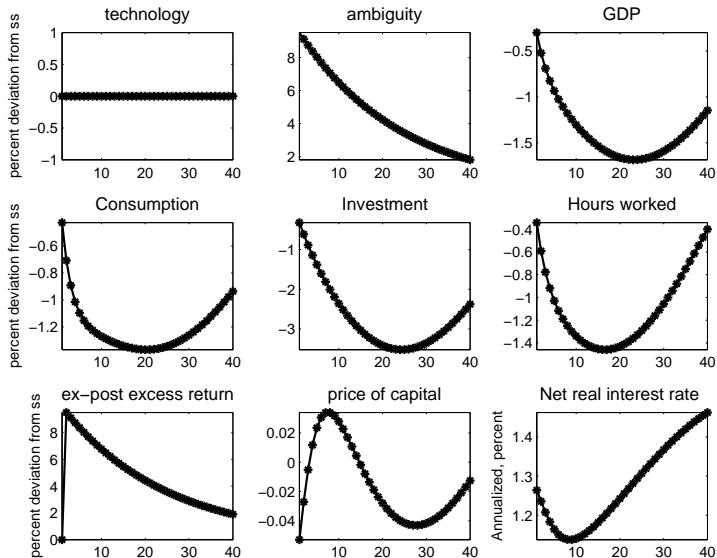
# Role of ambiguity in fluctuations

- Variance decompositions: business cycle frequency

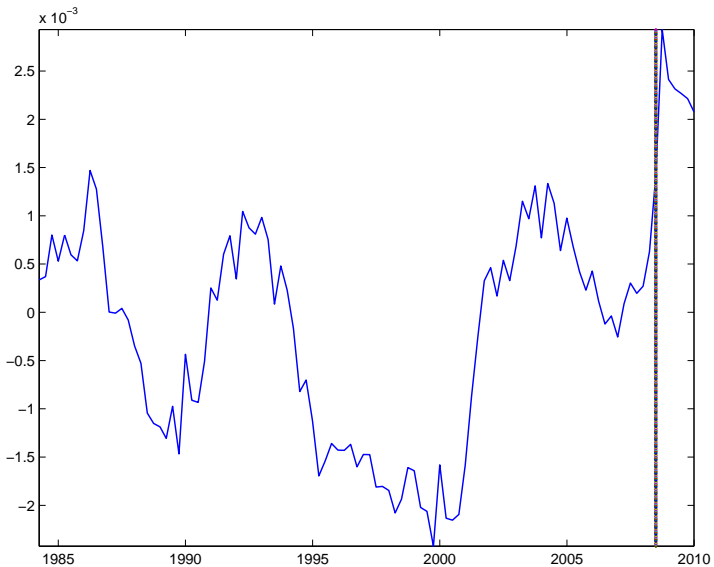
Shock/Var.	Output	Consumption	Investment	Hours
Ambiguity	27	51	14	30
Stationary techn.	11	13	9	2
Efficiency of invest.	33	7	53	32
Stochastic Growth	7	7	6	13
Price mark-up	12	12	12	13

- ▶ any other shocks  $< 5\%$  for above variables.
- ▶ long-run theoretical decomposition:  $\varepsilon_{a,t}$  about 50% of fluctuations.

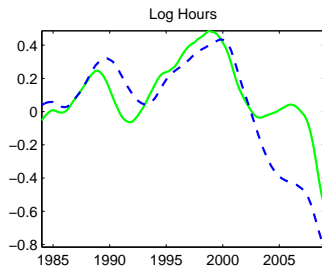
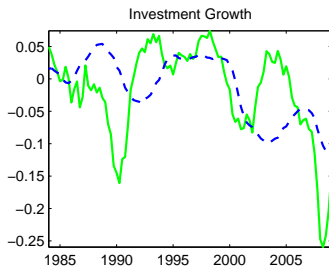
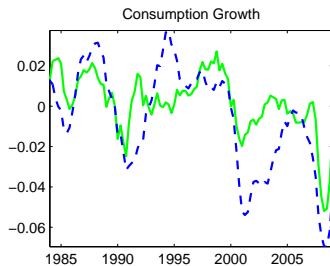
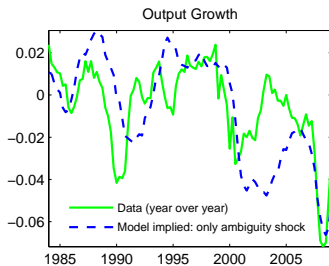
# Dynamics: loss of confidence



# Estimated ambiguity path



# Historical shock decomposition



# Welfare cost of fluctuations through ambiguity

Setting  $\sigma_z = 0$  vs estimate  $\implies \bar{a} = 0$  vs estimate

- Welfare:  $\bar{V} \equiv$  Value function under "zero risk steady state" (with estimated  $\bar{a}$ )

- ▶ Welfare cost of fluctuations, as % of  $C_{SS}(\bar{a} = 0)$ , due to:

- 1 ambiguity:

$$\lambda^{ambig} = [\bar{V} - V^{SS}(\bar{a} = 0)] (1 - \beta)\beta^{-1} = 13\%$$

- 2 risk (known probability distributions):

$$\lambda^{risk} = V_{\sigma\sigma}(1 - \beta)\beta^{-1} = 0.01\%$$

★  $V_{\sigma\sigma}$  : effect of fluctuations in  $\varepsilon_{z,t+1}$  in a second order approx. of  $V(\cdot)$ .

- Other vars: Output, Capital, Consumption, Hours lower by 15%

# Conclusion

- Standard business cycle model with ambiguity aversion:
  - ▶ recursive multiple priors preferences.
  - ▶ ambiguity about mean productivity.
  - ▶ discipline from modeling concern with nonstationarity
- With ambiguity, uncertainty shocks have 1st order effects:
  - ▶ can apply standard linearization techniques for solution and estimation
  - ▶ work like “unrealized” news shocks with bias
  - ▶ potentially large role in business cycle
- Next
  - ▶ characterize further essentially linear settings

# Parametrization

- Recall

$$a_t - \bar{a} = \rho_a (a_{t-1} - \bar{a}) + \sigma_a \varepsilon_{a,t}$$

- Restrictions: process  $a_t$  s.t.

- $a_t$  is positive:

$$\bar{a} - m \frac{\sigma_a}{\sqrt{1 - \rho_a^2}} \geq 0$$

- $a_t$  is bounded by the discipline of the non-stationary argument

$$\bar{a} + m \frac{\sigma_a}{\sqrt{1 - \rho_a^2}} \leq 2\sigma_z$$

- Scale

$$\bar{a} = n\sigma_z, \quad n \in [0, 1]$$

- Directly estimate  $n, \rho_a$ .



## Solution method: Steps

- Find deterministic “distorted” steady state  $x_o$  based on

$$z_o = \exp\left(\frac{-\bar{a}}{1 - \rho_z}\right)$$

- Linearize around distorted SS: Find  $A, B$  :

$$x_t - x_o = A(x_{t-1} - x_o) + BP(s_{t-1} - s_o) + B(\Xi_t - \Xi_o)$$

$$s_t = \begin{bmatrix} s_t^* \\ \hat{z}_t \\ a_t \end{bmatrix} = \begin{bmatrix} \rho & 0 & 0 \\ 0 & \rho_z & -1 \\ 0 & 0 & \rho_a \end{bmatrix} \begin{bmatrix} s_{t-1}^* \\ \hat{z}_{t-1} \\ a_{t-1} \end{bmatrix} + \Xi_t$$

- Equilibrium:

- ▶ True DGP dynamics:

$$\hat{z}_t = \tilde{E}_{t-1}\hat{z}_t + a_{t-1}$$

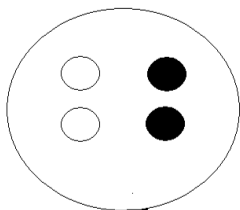
- ▶ Endogenous variables:

$$x_t - x_o = A(x_{t-1} - x_o) + BP(s_{t-1} - s_o) + B(\hat{\Xi}_t - \Xi_o)$$

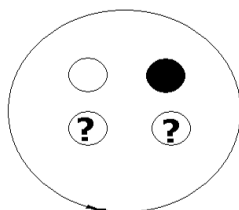
$$\hat{\Xi}_t = \begin{bmatrix} a_{t-1}/\sigma_z \\ 0_{(n-1) \times 1} \end{bmatrix}$$

# Ellsberg Paradox

Risky Urn



Ambiguous Urn



- bet on black from risky urn  $\succ$  bet on black from ambiguous urn
- bet on white from risky urn  $\succ$  bet on white from ambiguous urn
- expected utility cannot capture choices, but  $\min_{p \in \mathcal{P}} E^p[u(c)]$  can!

► Ambiguity